ST0N 1625Nx\SR
ST0N 1625Nx\DR

DATA SHEET

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1 SAFETY

This product is a String Monitoring System (SMU) and its application is the monitoring of photovoltaic systems. From an electrical point of view, by their nature, photovoltaic systems operate in direct current and with very high voltage and current values.

		Safety : General Conditions
⚠️	**DANGER**	- This product is therefore designed to operate with direct current voltage values up to 1500 VDC. This voltage value is potentially fatal. Voltage values between 24 VDC and 1500 VDC are therefore present on this product. - All transducers connected to the auxiliary input connectors must be isolated at 1500 VDC. These transducers are PT100 and, in the case of the ST2N and ST2 series, also transducers with 0/10 VDC and 0/20 mA output (typically anemometers)

		Safety : Installation and replacement precautions
⚠️	**DANGER**	- The installation and / or replacement of this product must take place in absolute safety, therefore it is necessary to proceed with the installation and / or replacement of this product which is housed inside the field panel after disconnecting the power and dangerous voltages from solar panels. - In any case, any intervention involving the handling of the SMU must be carried out by skilled and trained technicians equipped with insulation gloves designed for voltage values up to 1500 VDC and after disconnecting any voltage and current from the solar panels.

		Important Safety Instructions
⚠️	**DANGER**	- Contact with wiring terminals inside the device can cause death by electric shock! - Before to operate inside cards with tester, or with other measurement equipment, it is mandatory TO OPEN fuses and other components that can bring high level voltage inside cards.
⚠️	**WARNING**	- Please check all input and output wire terminals in case of high DC voltage and make sure there is no voltage before electrical connection to avoid electric shock! - Do not touch the live parts of the input and output sides to avoid electric shock when checking or maintaining the device. - All installation and wiring connections must be made by qualified technical personnel only.
⚠️	**CAUTION**	- All wiring and operation must comply with the requirements of the relevant local standards of the device. - Check the device and make sure there are no problems with the installation before putting it into operation! - Connect the wires to the positive and negative marked positions of the device to avoid the risk of short circuit, ensure personal safety and keep the device in normal operation.
ℹ️	**IMPORTANT**	**Reference to current standards** For any other consideration, safety precaution, it is absolutely necessary, before carrying out any installation and / or replacement of the SMU, to refer to the regulations in force regarding the construction of combiner boxes.

2 GENERAL NOTES

2.1 Introduction

The ST0N module to string control, allow to monitoring current and voltage generated by photovoltaic panels strings. For example is possible connect each other 32 PV panels at 36 V to each string channel, with positive pole connected each other. The negative pole of each string is brought to the dedicated input, like in the following picture :
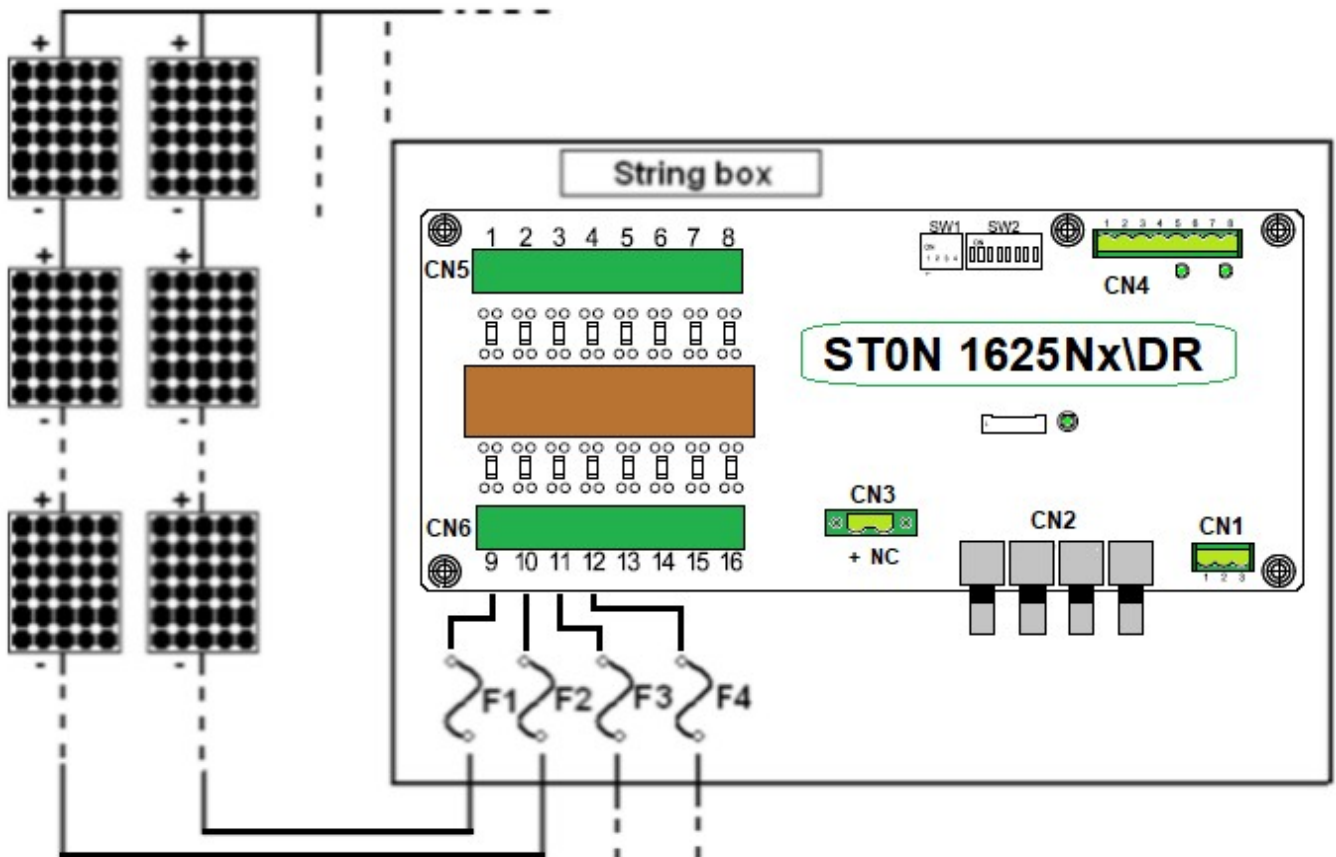
After the strings input connector, on the ST0N board there is a resistor, it is necessary to detect the current follow :
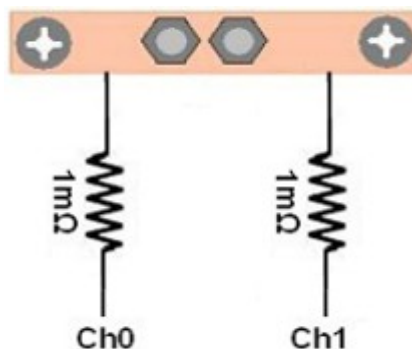
and finally a copper bar connect all the negative poles, thus creating a common 0 V.

The ST0N board also provides two digital inputs and an on-board sensor which allow to measure the temperature.
The digital inputs allows to detect the arrester state and the power disconnector switch state.
Is possible communicate with the ST0N board through a Fiber Optic connection. Using **Modbus RTU protocol**, or with **IEC 60870-5-101 protocol**, is possible monitoring all the physical quantities measured (temperature, currents, voltage). Moreover

is possible keep monitored the fuses status on the string box, through the reading of an internal register on memory map (30034).
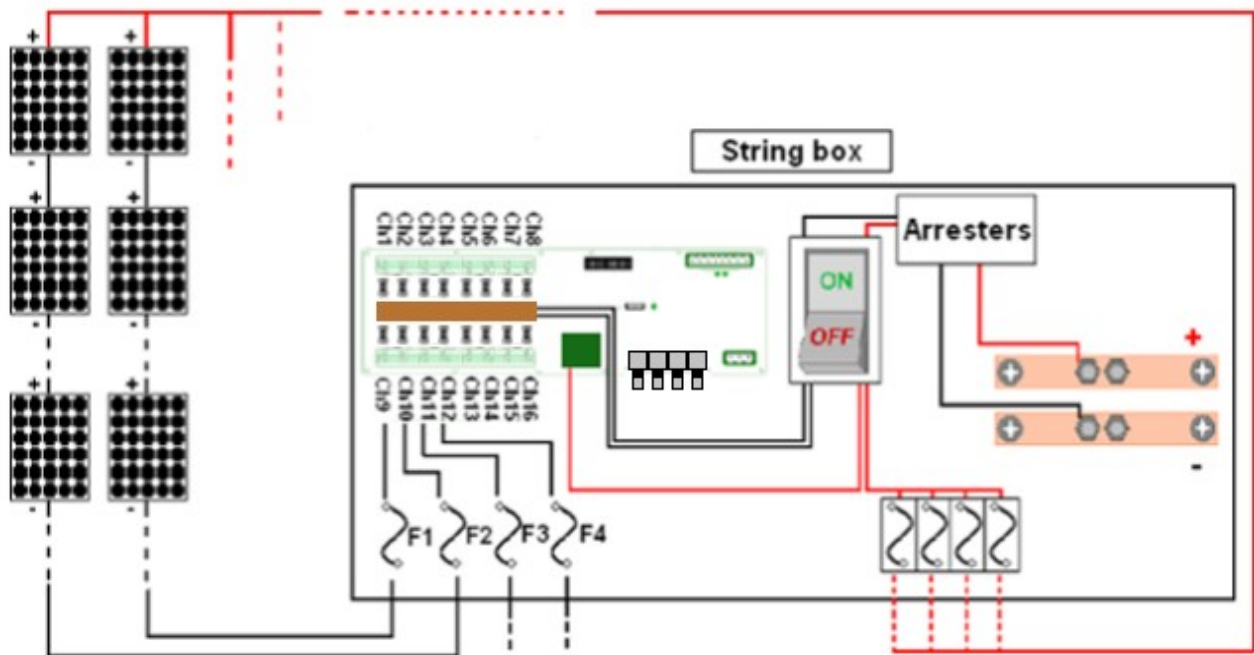
In the following image there are the "ST0N string controller" with all the wiring. Obviously isn't necessary connect all the specified devices, they are indicated to give a connection general idea.
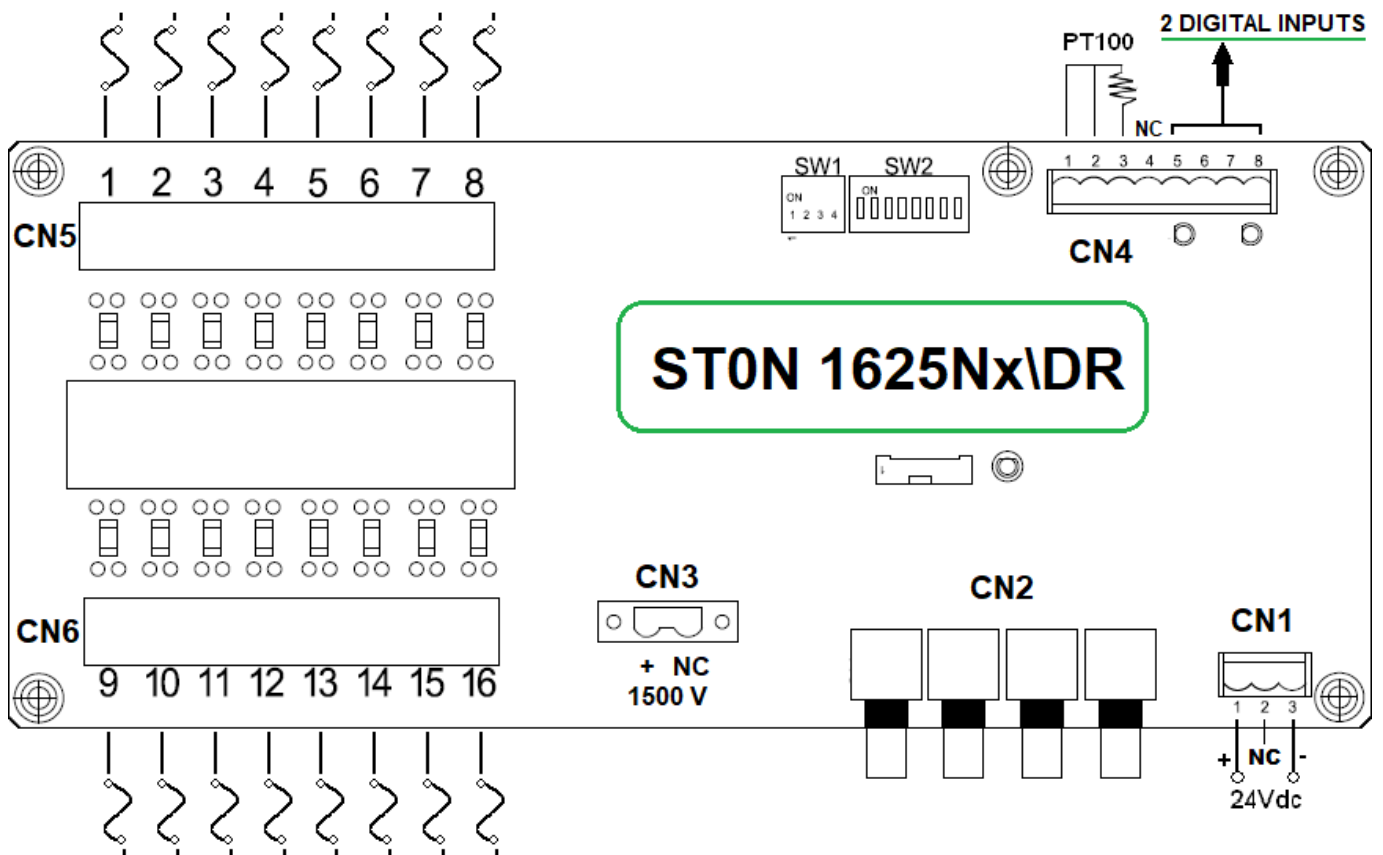
3 HARDWARE CHARACTERISTICS

3.1 Hardware Characteristics

ELECTRIC CHARACTERISTICS	
Microprocessor	STM32F303
Power supply	24 Vdc
Power consumption (W)	< 3 W
Maximum number of monitored strings	16
Maximum common voltage	1500 V with precision better than 0,5 %
Max. current for each string	25 A
Range of measurement	0 … 400 A
Current reading accuracy	Better than 0,15 %
Current reading precision	Typical 0,5 %
Communication	Fiber Optic (**Modbus RTU** or **IEC 60870-5-101**)
Digital Inputs	2 digital inputs 24 Vdc PNP
Analog inputs	1 input PT100 + 1 on board temperature sensor to know the temperature inside the string box panel
Working temperature's range	From -40 to +85 °C
Working atmosphere	Without corrosive gas
ID Address	Defined by dip-switches
Size (naked)	249,8 x 108 mm
Size (with support for din rail bar)	253,8 x 128 mm
Working humidity	Lower 95 % without condensation
MTBF	> 500000 hours
Maximum Operating Altitude	5000 meters
Minimum Current	1 A (programmable)
Minimum Voltage	100 V (programmable)

Minimum Current / Minimum Voltage: from Firmware Version : **1.31** forward

N°	Type of resources	Symbol	Terminal Block
1	Sensor on board to read the temperature (precision better than 1,5%).	**T2**	**On board**
1	Fiber Optic connection : is used to connect many "ST0N string controllers" into a network or to a PC. Is possible select the communication characteristics with some dip-switches on board (node address, baud rate, parity, and communication protocol, that may be **Modbus RTU** or **IEC 60870-5-101**). It's divided in 2 connectors (Single Ring) or 4 connectors (Double Ring).	**FIBER OPTIC**	**CN2**
1	PT100 input (from -20 to +120 °C) to temperature reading, with precision better than 1,5 %	**T1**	**CN4**
2	PNP digital inputs 24 Vdc, typically used to arrester connection, switches or other devices.	**INP0, INP1**	**CN4**
16	This board can manage the current reading of 16 strings until 25 A with typical precision of 0,5% and a temperature between -40 and +85 °C	**Ch1 … Ch16**	**CN5, CN6**

3.2 Power Dissipation

First of all we have to distinguish from "**power dissipation**" to "**power consumption**" : power dissipation is the total amount of power dissipated by the SMU, that is splitted in two parts : the part needed to supply the electronics and the part dissipated by the shunts used to measure the string currents. Only the part needed by the electronic (the power consumption) is to be supplied by the external 24 V power supply, this part is fixed and is typically less then **3 W** (125 mA) for all models of SMU.

The part dissipated by the shunt is variable and depends by the number of shunts and by the current that flows into them. To calculate the dissipation of each channel you can use the following formula, valid for all the SMU model :

Shunt_Power = current * current * 0.001 (where 0.001 is the ohmic resistance of the shunt)
than you have to multiply for the number of channels (shunts)

- **Example ST0N1625 : if you consider a current of 25 A you have :**
  25 * 25 * 0.001 * 16 = 10.0 W

- **Example ST0N1625 : if you consider a current of 12.5 A you have :**
  12.5 * 12.5 * 0.001 * 16 = 2.5 W

This part of power is not to be supplied by the 24 V external power supply because it is directly generated by the current from PV strings.

IMPORTANT

It is possible to power the board directly from PV panels using an insulated DC/DC power supply for PV usage. Of course keep in mind that before the sunrise and after the sunset the voltage from the PV is zero, so the DC/DC converter does not work and the board is not powered.

3.3 Connector : CN1

POWER SUPPLY
24 Vdc
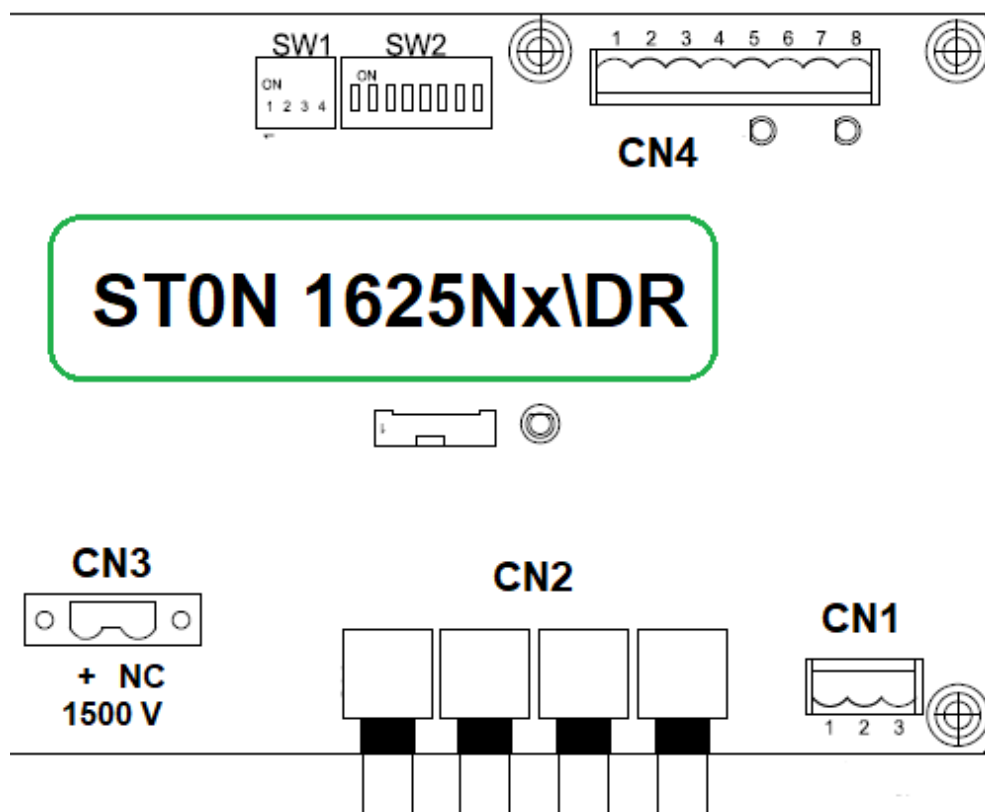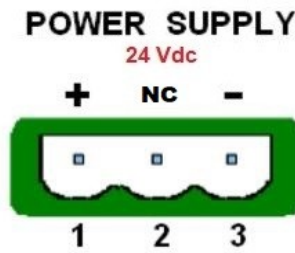
3.4 Connector : CN3

To read the voltages, is necessary connect the negative of the panel's string to one channel and the positive to the positive pin of connector CN3. You'll find the voltage value on 30040.

VOLTAGE (0...1500V)
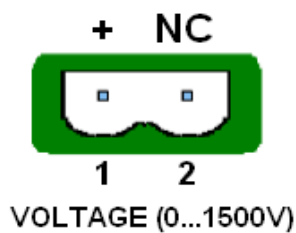
3.5 Connector : CN4

To know when a switch (for example the general one) is ON or OFF, there are two digital inputs PNP 24 Vdc on terminal block CN4. Each digital input status is indicated also by a led status on board. You need to use the pins 5, 6, 7 and 8. Inside the memory map the bits from 0 to 1 of register 30001 are the digital input status.
Is possible connect one PT100 to read the external temperature. The PT100 could be 2 or 3 wires, it will be connected in the following way to terminal block CN4. You can find this temperature on register 30044.

DIGITAL INPUTS
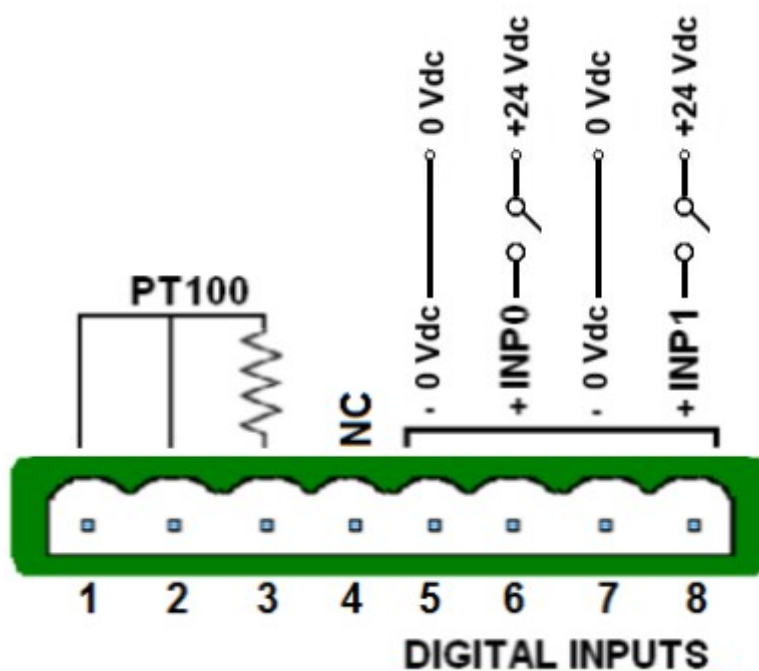
3.6 Board Dimensions

ST0N1625NC/DR
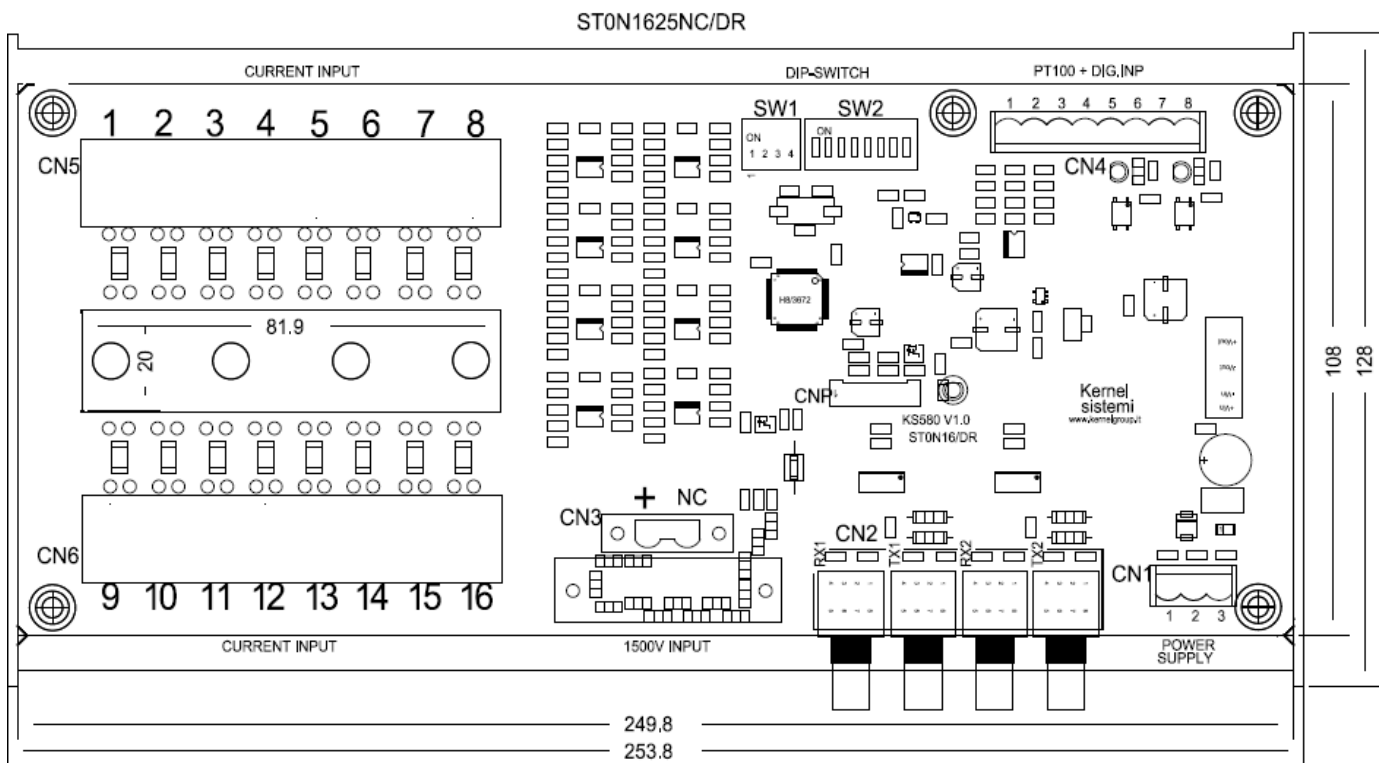
3.7 Memory Protection

Memory is always protected by writing! In order to enable writing for a limited time (10 minutes), you have to write :

Value : 0x5555 Hex
Modbus Register : 40100

3.8 Busbar

Busbar dimensions : (n.1 BAR component side + n.1 BAR welding side)

82

20   23.5   23.5   23.5
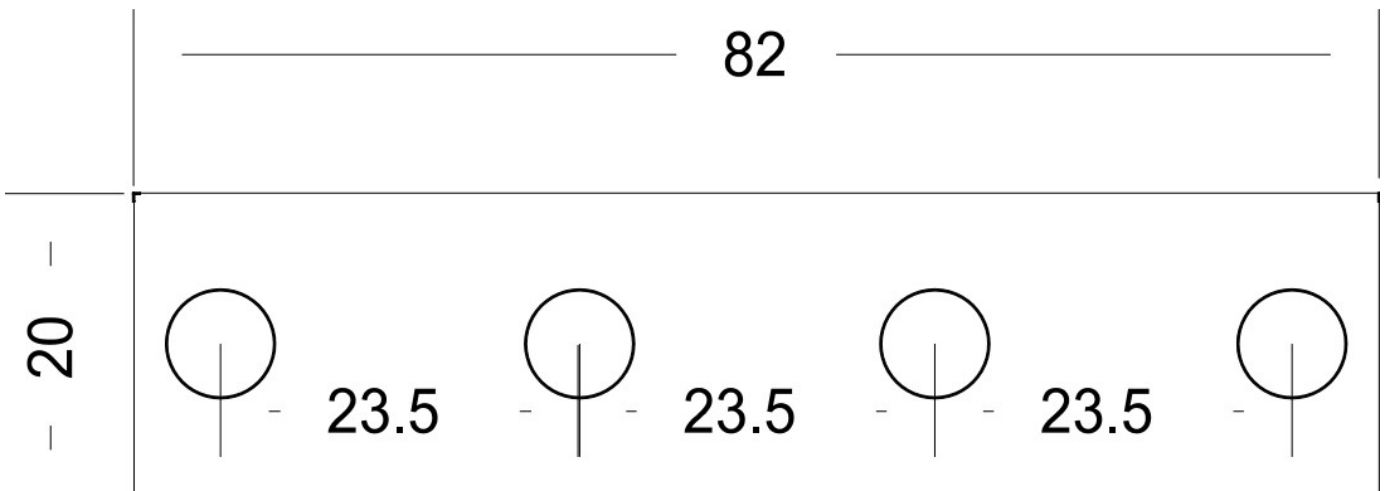
TOLERANCE FOR ALL OF +/- 0.05mm
TIN BAR WITH 4 HOLES (FOR M6 SCREWS)

Examples of busbar connection :
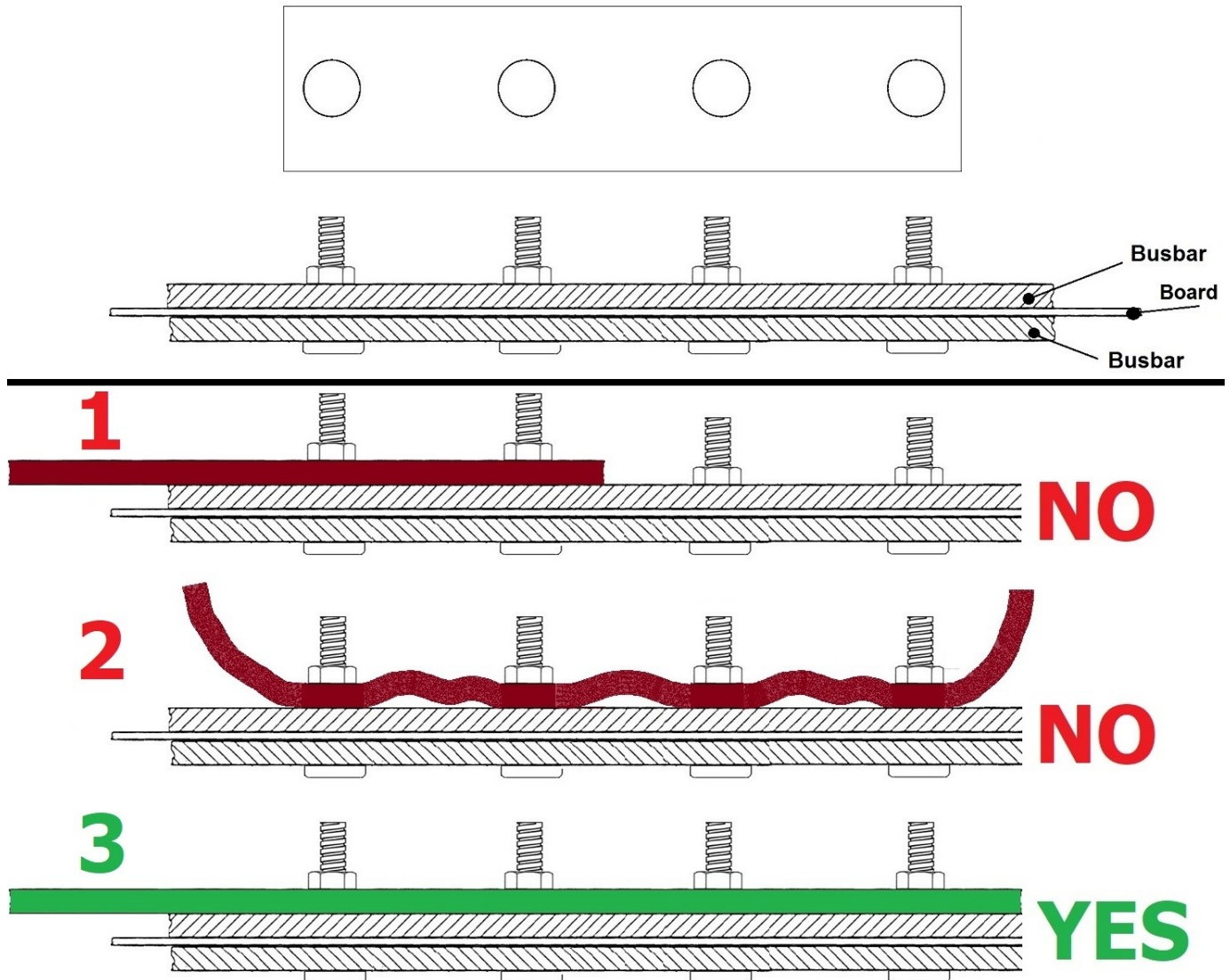
If it is necessary to "**extend**" the busbar, the following fundamental rules must be followed :

1. The added bar must take the whole bar and be connected to all the bolts (with the correct tightening torque).

2. It must not have curves or irregularities.

3. It must be absolutely flat so as to be perfectly in contact on the whole surface of the bar.
This connection busbar **MUST** be perfectly planar.
It is therefore necessary to check that these busbars are perfectly planar **BEFORE** fixing them to the busbar of the board.

It is necessary FIRST to fix the "busbar connection to the Switch Disconnector" to the BOARD, then perform the fastening of this busbar to the Switch Disconnector. In doing so, the perfect contact between the "busbar connection to the S.D." and the busbar on the board is guaranteed.

ATTENTION

The dimensions of the bar must be calculated according to the value of the **MAXIMUM CURRENT**
(follow the appropriate regulatory tables)
As an alternative to the bar, it is possible to connect more CABLES to the busbar on the board : also in this case the cables must be appropriately sized according to the value of the **MAXIMUM CURRENT**
(follow the appropriate regulatory tables).

3.9 Dip-switches
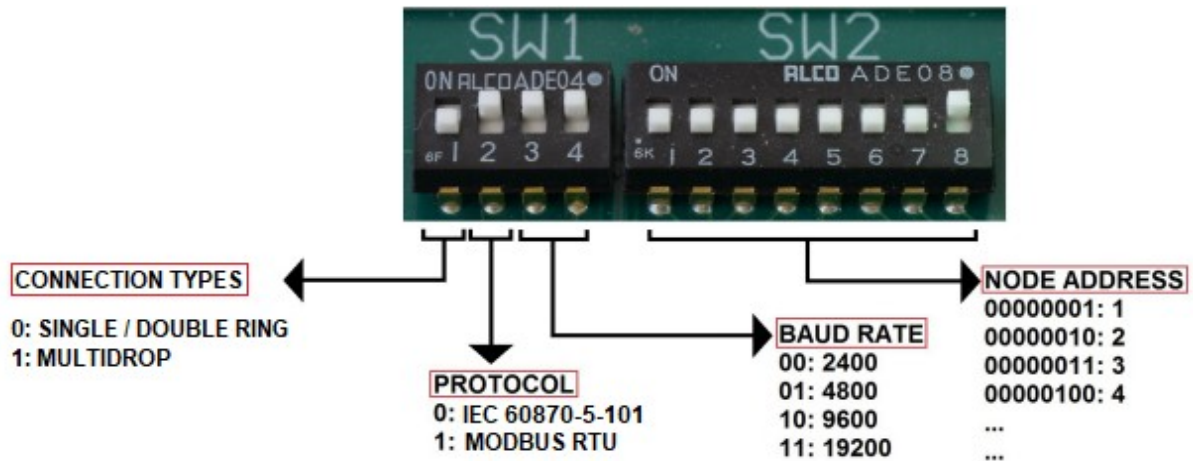
Some dip-switches examples :
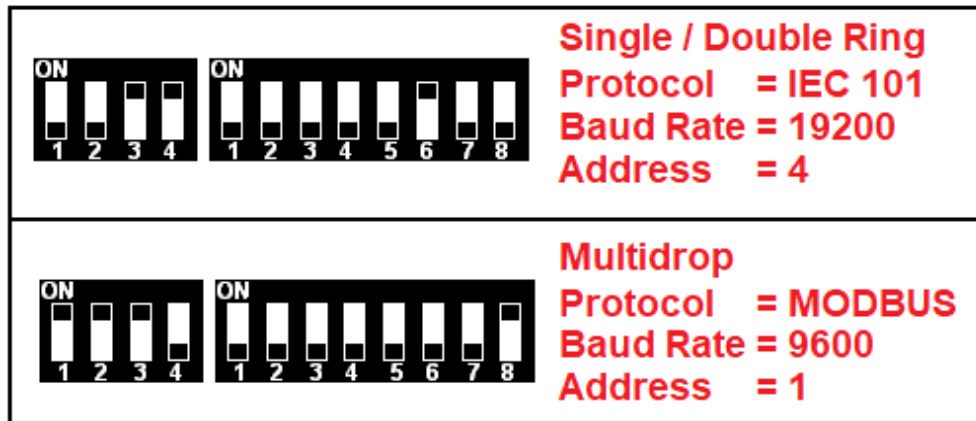
3.10 Fixing system of the naked board (without supporting box)

To fix the naked board (without case) is necessary use plastic spacers with dual clutch.
The plastic spacers must be 4x20 mm or 4x25 mm (4 mm is the hole diameter on the board).
Look the below picture.

3.11 Status led

On the board there is a status led which with its blinking show the board status.
There are two possible different blinking ways : blinking each 0,5 sec, or blinking faster. If the blinking is 0,5 sec ON and 0,5 sec OFF, it means that the board is ready to communicate with an external device, instead if the blinking is faster than 0,5 sec, it means that the board is in test mode with all the dip-switch OFF. In this way the board isn't ready to communicate with an external device.

3.12 Informations about wires and connectors

CHANNEL CONNECTOR	
Nominal Cross Section	16 mm²
Stripping length	10 mm
Conductor cross section AWG/kcmil	20 to 6
Screw	M4
Min / Max Torque	1.20 Nm / 1.50 Nm [10.6 Lbf-In / 13.3 Lbf-In]
Operating temperature	depends on the derating curve
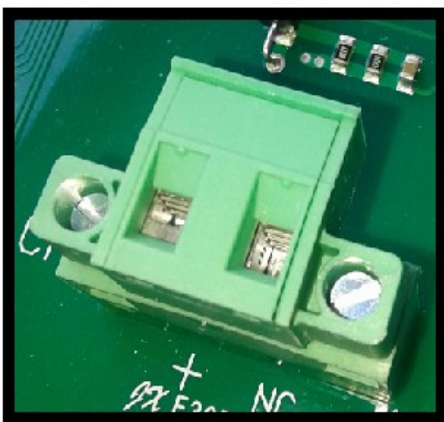
VOLTAGE CONNECTOR	
Wire Section	2.5 mm² / 0.20-2.5 mm²
Stripping length	7 mm
Conductor cross section AWG/kcmil	24 to 12
Screw	M3
Min / Max Torque	0.50 Nm / 0.60 Nm [4.4 Lbf-In / 5.3 Lbf-In]
Operating temperature	-40°C ÷ (depends on the derating curve)
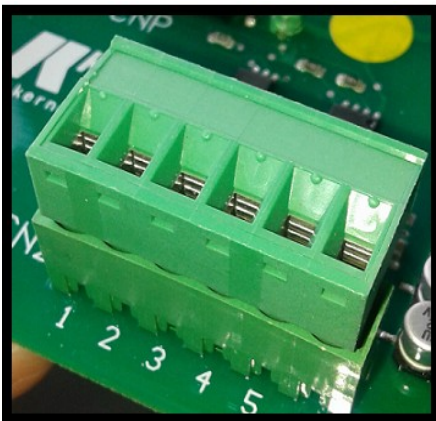
OTHER CONNECTORS (Power Supply ...)	
Wire Section	2.5 mm² / 0.34-2.5 mm²
Stripping length	7 - 8 mm
Solid Wire (AWG)	12-24 / 14-22
Screw	M3
Max Torque	0.56 Nm [5.0 Lbf-In]
Operating temperature	-40°C ÷ +115°C

Copper Bar	
Min / Max Torque	2.2 Nm / 2.5 Nm [19.5 Lbf-In / 22.1 Lbf-In]

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3.13 Connection Types

Is possible connect ST0N with 3 different configurations as below! The 3 types are the following :
1. **"Single Ring or Single Connection"**
2. **"Double Ring or Double Connection" [Redundant]**
3. **"Multidrop Connection" [Redundant]**

The final result is as schematized here below :

SINGLE RING / SINGLE CONNECTION
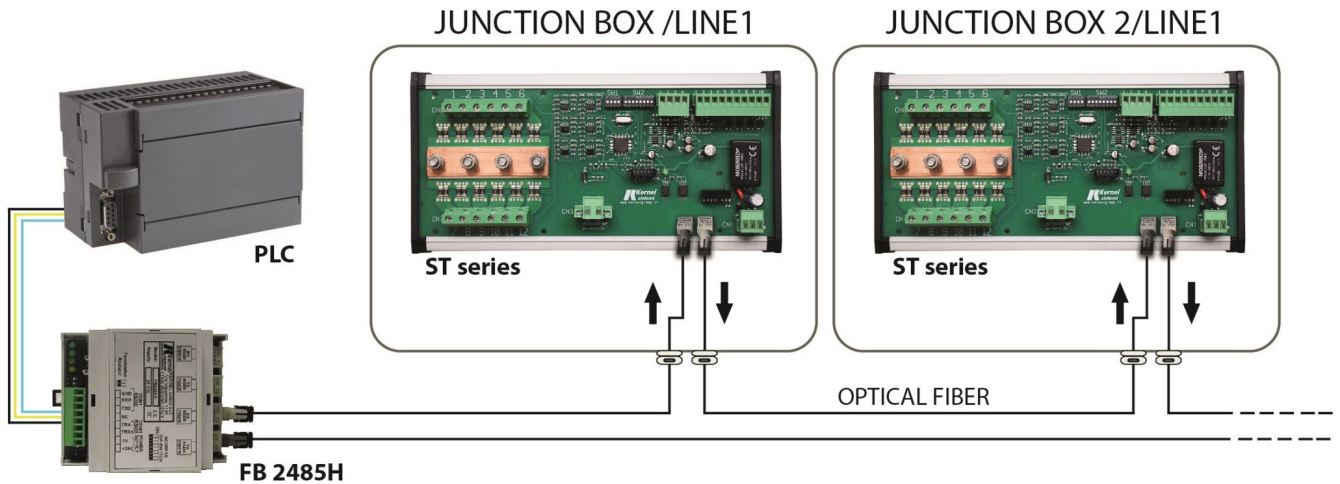
Protocol = MODBUS or IEC 60870-5-101

DOUBLE RING / DOUBLE CONNECTION [REDUNDANT]
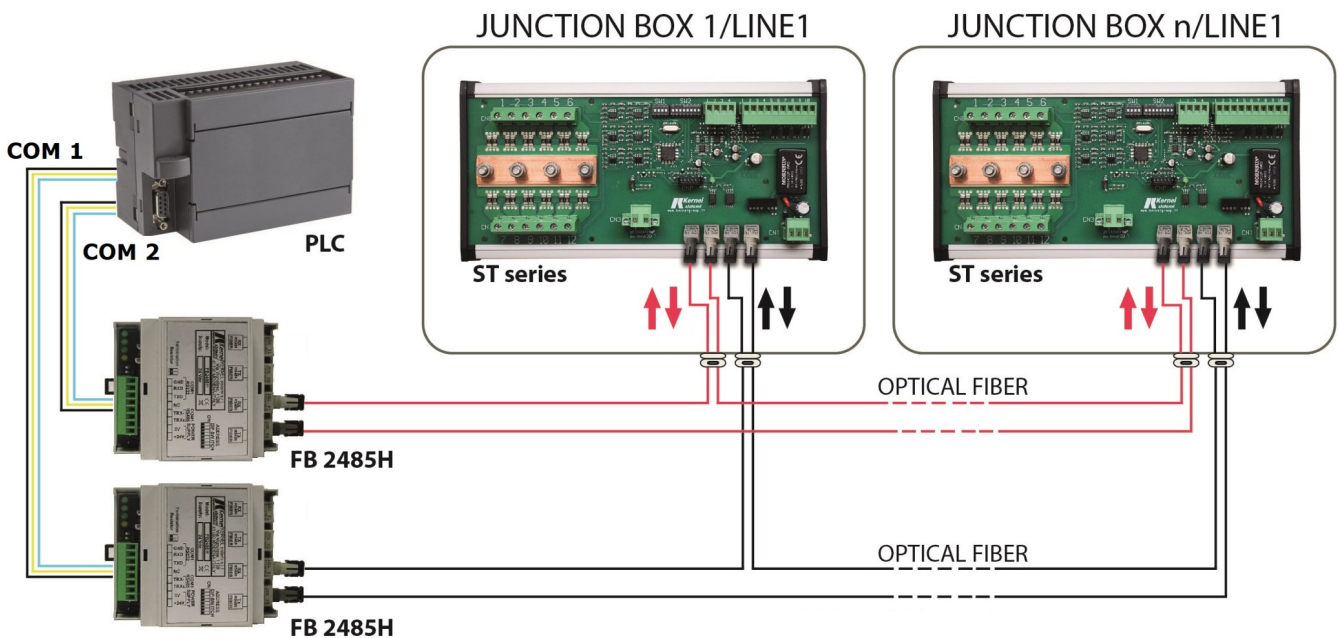
Protocol = MODBUS or IEC 60870-5-101

MULTIDROP CONNECTION [REDUNDANT]
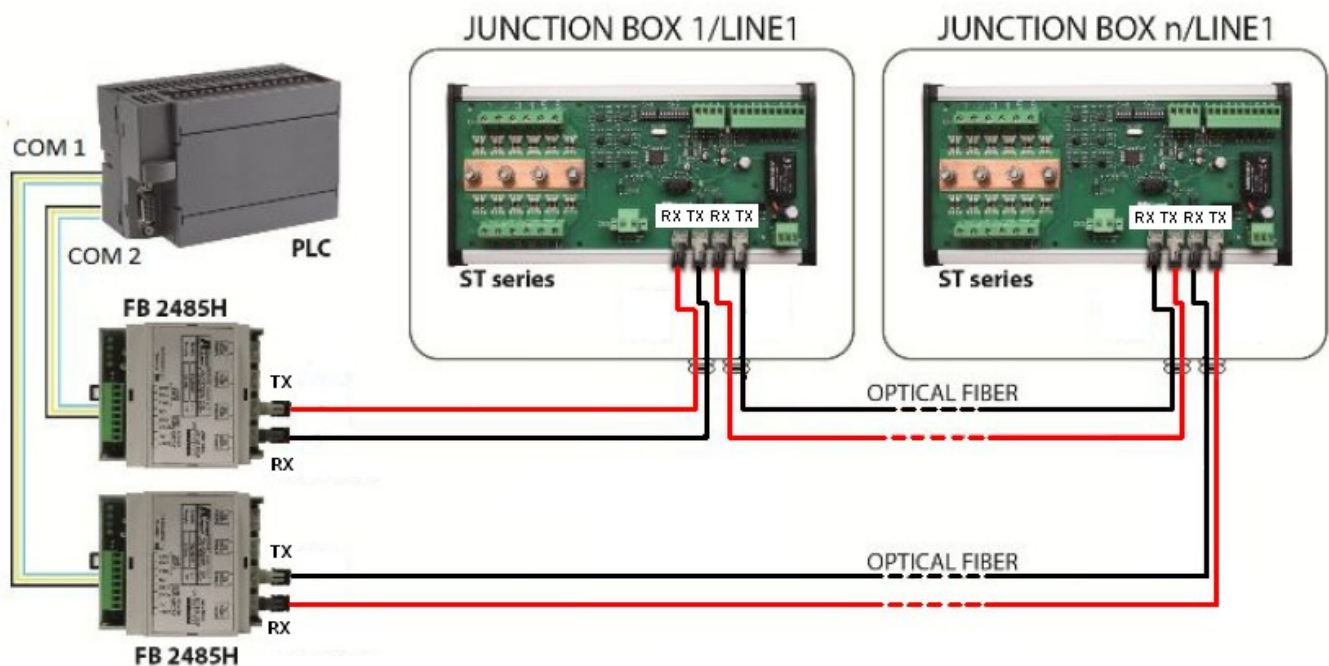
Protocol = MODBUS or IEC 60870-5-101

3.14 Scada – PLC

Typically the PLC communicates via Modbus TCP / IP protocol with the SCADA in the control room with Ethernet or fiber optic or wireless connection.
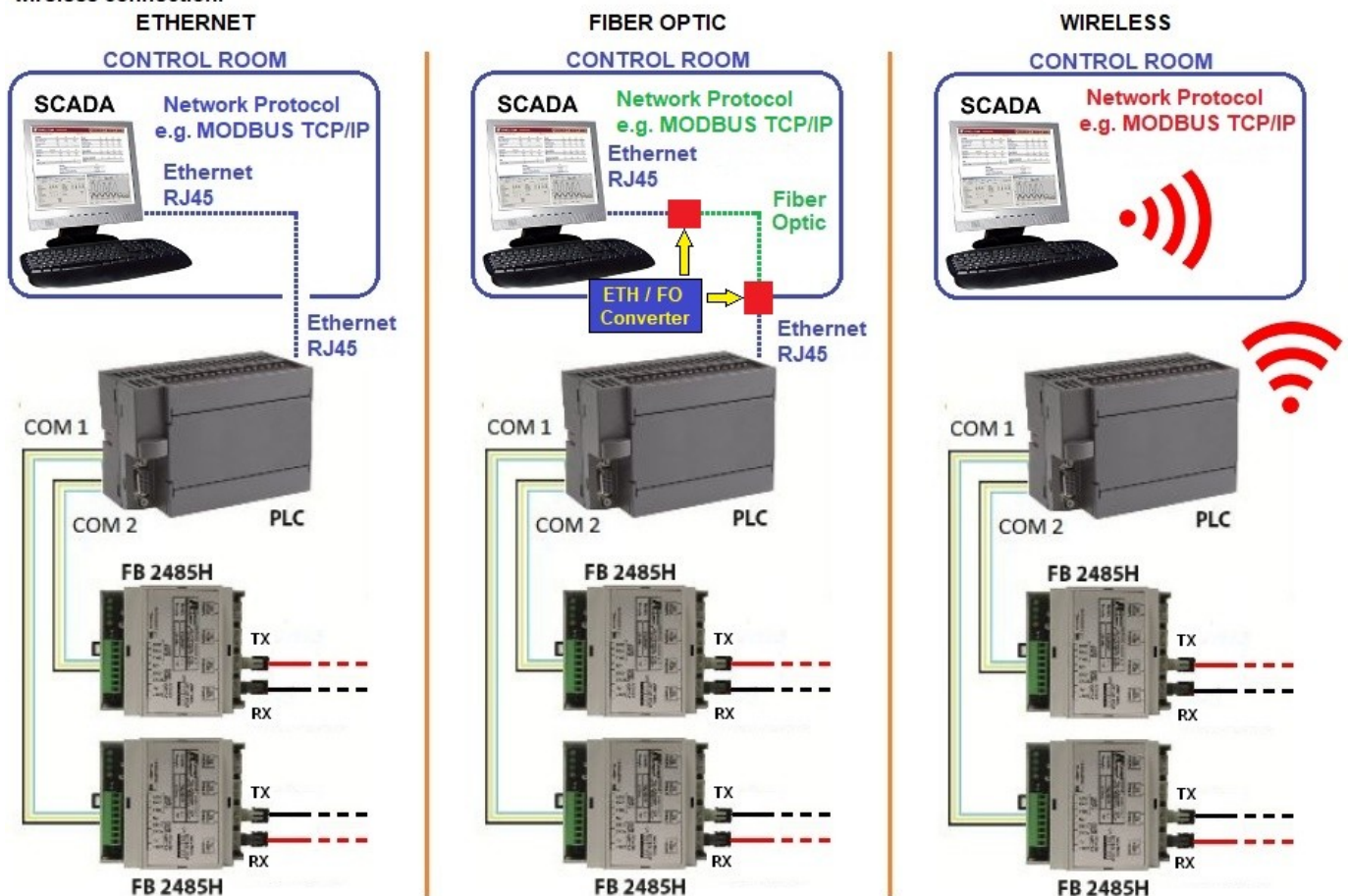
4 MEMORY MAP

The ST0N has the following memory map, it's made of 16 bits locations (1 word) called "REGISTER". Because each REGISTER is composed by 16 bits, its maximum value will be 65535.

MODBUS Register	TYPE	DESCRIPTION
30001	RO	Inputs
30002	RO	Inst Curr Str_01 (mA [0...25000])
30003	RO	Inst Curr Str_02 (mA [0...25000])
30004	RO	Inst Curr Str_03 (mA [0...25000])
30005	RO	Inst Curr Str_04 (mA [0...25000])
30006	RO	Inst Curr Str_05 (mA [0...25000])
30007	RO	Inst Curr Str_06 (mA [0...25000])
30008	RO	Inst Curr Str_07 (mA [0...25000])
30009	RO	Inst Curr Str_08 (mA [0...25000])
30010	RO	Inst Curr Str_09 (mA [0...25000])
30011	RO	Inst Curr Str_10 (mA [0...25000])
30012	RO	Inst Curr Str_11 (mA [0...25000])
30013	RO	Inst Curr Str_12 (mA [0...25000])
30014	RO	Inst Curr Str_13 (mA [0...25000])
30015	RO	Inst Curr Str_14 (mA [0...25000])
30016	RO	Inst Curr Str_15 (mA [0...25000])
30017	RO	Inst Curr Str_16 (mA [0...25000])

...

30034	RO	Fuse status (Ch01...Ch16)

...

30040	RO	Inst V_1 (V [0...1500])

...

30044	RO	Inst T_1 (°C [-20...+120]) - PT100
30045	RO	Inst T_2 (°C [-22,0...+83,0]) – on board

...

30047	RO	Sum of all currents (A / 10)
30048	RO	Power (W) - LSW
30049	RO	Power (W) - MSW

...

|		
30052	RO	RMS Curr Str_01 (average value on last 6 seconds)
30053	RO	RMS Curr Str_02 (average value on last 6 seconds)
30054	RO	RMS Curr Str_03 (average value on last 6 seconds)
30055	RO	RMS Curr Str_04 (average value on last 6 seconds)
30056	RO	RMS Curr Str_05 (average value on last 6 seconds)
30057	RO	RMS Curr Str_06 (average value on last 6 seconds)
30058	RO	RMS Curr Str_07 (average value on last 6 seconds)
30059	RO	RMS Curr Str_08 (average value on last 6 seconds)
30060	RO	RMS Curr Str_09 (average value on last 6 seconds)
30061	RO	RMS Curr Str_10 (average value on last 6 seconds)

30062	RO	RMS Curr Str_11 (average value on last 6 seconds)	
30063	RO	RMS Curr Str_12 (average value on last 6 seconds)	
30064	RO	RMS Curr Str_13 (average value on last 6 seconds)	
30065	RO	RMS Curr Str_14 (average value on last 6 seconds)	
30066	RO	RMS Curr Str_15 (average value on last 6 seconds)	
30067	RO	RMS Curr Str_16 (average value on last 6 seconds)	

...

30084	RO	RMS V_1 *(V [0...1500])* (average value on last 6 seconds)

...

30088	RO	RMS T_1 *(°C [-20...+120])* (average value on last 6 seconds)
30089	RO	RMS T_2 *(°C [-22,0...+83,0])* (average value on last 6 seconds)

...

30091	RO	RMS Sum of all currents (A / 10) (average value on last 6 seconds)
30092	RO	RMS Power (W) - LSW (average value on last 6 seconds)
30093	RO	RMS Power (W) - MSW (average value on last 6 seconds)

...

30201	RO	Firmware Version	READ ONLY
30202	RO	SMU Model	READ ONLY
30203	RO	Channels Number	READ ONLY
30204	RO	Shunt Type	READ ONLY
30205	RO	End Scale	READ ONLY
30206	RO	Reserved for Future Use	RFU
30207	RO	Reserved for Future Use	RFU
30208	RO	Reserved for Future Use	RFU
30209	RO	Reserved for Future Use	RFU
30210	RO	Reserved for Future Use	RFU
30211	RO	Unique ID code [0]	READ ONLY
30212	RO	Unique ID code [1]	READ ONLY
30213	RO	Unique ID code [2]	READ ONLY
30214	RO	Unique ID code [3]	READ ONLY
30215	RO	Unique ID code [4]	READ ONLY
30216	RO	Unique ID code [5]	READ ONLY

...

40001	RW	Set up PARITY mode = 1 : None ; 2 : Even ; 3 : Odd
40002	RW	Offset Curr Str_01
40003	RW	Offset Curr Str_02
40004	RW	Offset Curr Str_03
40005	RW	Offset Curr Str_04
40006	RW	Offset Curr Str_05
40007	RW	Offset Curr Str_06
40008	RW	Offset Curr Str_07
40009	RW	Offset Curr Str_08
40010	RW	Offset Curr Str_09
40011	RW	Offset Curr Str_10
40012	RW	Offset Curr Str_11

40013	RW	Offset Curr Str_12
40014	RW	Offset Curr Str_13
40015	RW	Offset Curr Str_14
40016	RW	Offset Curr Str_15
40017	RW	Offset Curr Str_16

...

40034	RW	Answer Delay (msec)
40035	RW	Time Com Active (1/10 sec.)
40036	RW	Parity (1 = None, 2 = Even, 3 = Odd) = 40001
40037	RW	Fuse Threshold

...

40040	RW	Offset V_1

...

40044	RW	Offset T_1
40045	RW	Offset T_2

...

40047	RW	Minimum Current (Default = 1 A)
40048	RW	Minimum Voltage (Default = 100 V)

...

40052	RW	Gain Curr Str_1
40053	RW	Gain Curr Str_2
40054	RW	Gain Curr Str_3
40055	RW	Gain Curr Str_4
40056	RW	Gain Curr Str_5
40057	RW	Gain Curr Str_6
40058	RW	Gain Curr Str_7
40059	RW	Gain Curr Str_8
40060	RW	Gain Curr Str_9
40061	RW	Gain Curr Str_10
40062	RW	Gain Curr Str_11
40063	RW	Gain Curr Str_12
40064	RW	Gain Curr Str_13
40065	RW	Gain Curr Str_14
40066	RW	Gain Curr Str_15
40067	RW	Gain Curr Str_16

...

40090	RW	Gain V_1

...

40094	RW	Gain T_1
40095	RW	Gain T_2

...

40101	RW	User Memory 01
40102	RW	User Memory 02
40103	RW	User Memory 03
40104	RW	User Memory 04

40105	RW	User Memory 05	
40106	RW	User Memory 06	
40107	RW	User Memory 07	
40108	RW	User Memory 08	

...

40201	RO	Shunt Type (= 30204)	READ ONLY
40202	RO	SMU Model (= 30202)	READ ONLY
40203	RO	Firmware Version (= 30201)	READ ONLY
40204	RO	Channels Number (= 30203)	READ ONLY
40205	RO	End Scale (= 30205)	READ ONLY
40206	RO	Reserved for Future Use	RFU
40207	RO	Reserved for Future Use	RFU
40208	RO	Reserved for Future Use	RFU
40209	RO	Reserved for Future Use	RFU
40210	RO	Unique ID code [0] (= 30211)	READ ONLY
40211	RO	Unique ID code [1] (= 30212)	READ ONLY
40212	RO	Unique ID code [2] (= 30213)	READ ONLY
40213	RO	Unique ID code [3] (= 30214)	READ ONLY
40214	RO	Unique ID code [4] (= 30215)	READ ONLY
40215	RO	Unique ID code [5] (= 30216)	READ ONLY

NOTES

Each "Offset Register" has 0 as default value. Each "Gain Register" has 1000 as default value. *The value 1000 means x1*, in this way, for example, is possible write 500 and make the value **x0,5**.

4.1 Memory Map Description

30001 : the first two bits of these register are the mirror status of the two digital inputs on the board (INP0, INP1 on CN4). So if 30001 = 0000000000000011 [bin] = 3 [dec], it means that all the two digital inputs are ON.

30002 ... 30017 : these registers contains the current value of the current reading on each channel. It is in mA

30034 : the sixteen bits of 30034 show if each channel current reading is under 200 mA or not. This threshold represent the fuse status.

30040 … 30049 : these registers show the value of some readings as the temperatures (T1 and T2), voltage reading (on connector CN3) etc…

30052 ... 30067 : these registers contains the average value on last 6 seconds of the current reading. Obviously these values are more stable than the instantaneous values show in registers 30002 … 30017

40001 : through this register is possible set the communication parity. The default value is zero, so "no parity"

40002 ... 40017 : these are the offset registers. These registers (whose default value is 0) allow to add a constant value to the current reading. This allow to adjust a possible reading error. For example if 30002 show 2300 (it means that channel CH1 read 2,3A), writing 40002 = 200 the new value of the reading will be 30002 = 2500 (it means that channel CH1 read 2,5A).

40052 ... 40067 : these are the gain registers. These registers (whose default value is 1000) allow to multiply a constant value to the current reading. This allow to adjust a possible reading error. For example if 30002 show 2300 (it means that channel CH1 read 2,3A), writing 40052 = 1500 the new value of the reading will be 30002 = 3450 (it means that channel CH1 read 3,45A, 2300 x 1,5 =3450).

40101 ... 40108 : these are 8 registers available to the user. They can contain data useful to the customer, for example a different progressive number for each board.

40201 : Shunt Type (= 30204) – READ ONLY

40202 : SMU Model (= 30202) – READ ONLY

40203 : Firmware Version (= 30201) – READ ONLY

40204 : Channels Number (= 30203) – READ ONLY

40205 : End Scale (= 30205) – READ ONLY

40206 ... 40209 : Not Used - Reserved for Future Use (RFU)

40210 ... 40215 : **Unique device ID register (96 bits)** (organized in six 16 bit words) that is unique for any board.
(= 30211 **...** 30216) – READ ONLY

The unique device identifier is ideally suited :
• for use as serial numbers (for example string serial numbers or other end applications).
• for use as part of the security keys in order to increase the security.
The 96-bit unique device identifier provides a reference number which is unique for any device and in any context. These bits cannot be altered by the user. The code is composed of the following parts :
```
UID [31:00] : X and Y coordinates on the wafer expressed in BCD format
UID [39:32] : WAF_NUM [07:00] > Wafer number (8-bit unsigned number)
UID [63:40] : LOT_NUM [23:00] > Lot number (ASCII encoded)
UID [95:64] : LOT_NUM [55:24] > Lot number (ASCII encoded)
```

4.2 Reading speed

The analogic values of the currents, the voltage and the temperature are read simultaneously 10 times per second (100 msec scan time), then are inserted in it's own FIFO (a FIFO for each analogic value), 16 values deep. The value read from the board is the mobile mean of the FIFO, so it is the mean of the last 16 read values (1.6 sec), updated every 100 msec. This is done to make the analogic readout more stable and it is a good compromise between speed and readout stability.
The instant values of the analogic are temporary stored into a hidden memory area, not accessible to the COM port.
The update time depend on the speed polling time of the SCADA and the communication baud rate.
The total time requested to read the board via com port is splitted into three times: *the query time*, *the latency time* and *the response time*.
The query time is the time needed by the SCADA to send the MODBUS query packet and depends on the baud rate (about 4 msec at 19200 baud rate).
The latency time is the time need by the board to process the query and prepare the answer, it is between 1 and 2 msec and it is independent on the baud rate.
The response time is the time needed byte the board to send the MODBUS answer packet, it's depend on the baud rate and on the number of registers read at a time, for a single register read at 19200 baud it is about 4 msec.
So at 19200 baud rate the total time needed to read a single register is about 10 msec., you have to add 1 msec every other register read, for example to read 16 registers with a single query will take 10 msec + 15 * 1 msec = 25 msec.
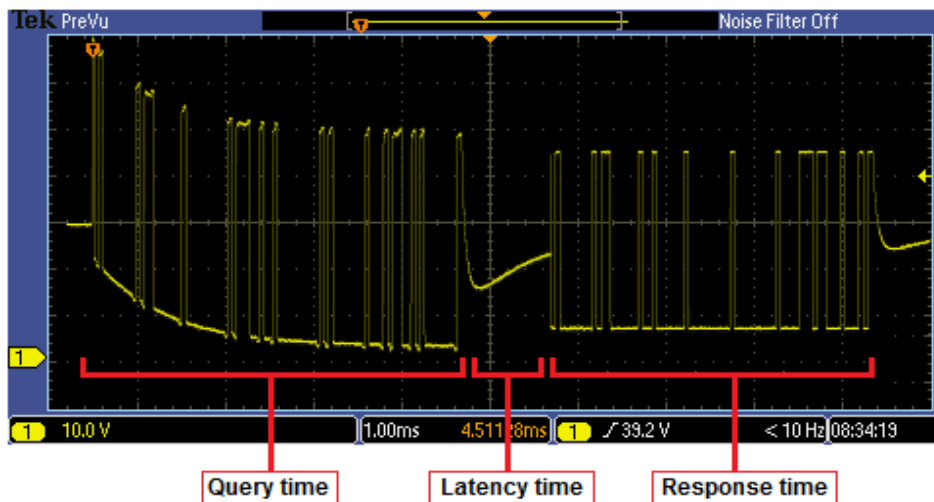
5 OPTICAL FIBER

5.1 OFC Network features

The characteristics of the fiber optic network achievable with the KERNEL SMUs with OFC interface on board are the following :

Max number of SMU that it's possible to connect in one network	**256**
Maximum distance between 2 consecutive SMUs	**2 - 3 KM** if the "fiber / connector" connections are correct
Recommended fiber optic features	**Multimode OM2 class or higher** **50/125 µm or 62.5/125 µm**
Connectors features	**ST**

IMPORTANT

The optical signal is regenerated internally to each **SMU** so that, each **SMU** retransmits the optical signal at the <u>maximum power</u>.
So the first **SMU**, connected to the **FB2485H** converter, receives the same level of optical signal that receives the last **SMU** of the network.

IMPORTANT

5.2 Optical Fiber Cable

The optical fiber cable which is necessary to the connection, mustbe a compatible cable :

Optical Fiber	**Compatible with :** **50/125 µm** **62.5/125 µm** **100/140 µm** **200 µm Plastic-Clad Silica (PCS) Fiber**
In Compliance with standard	**OM1, OM2, OM3, OM4**

5.3 Optical Fiber Connector

Here are indicated the characteristics of the optical fiber connector on the board :
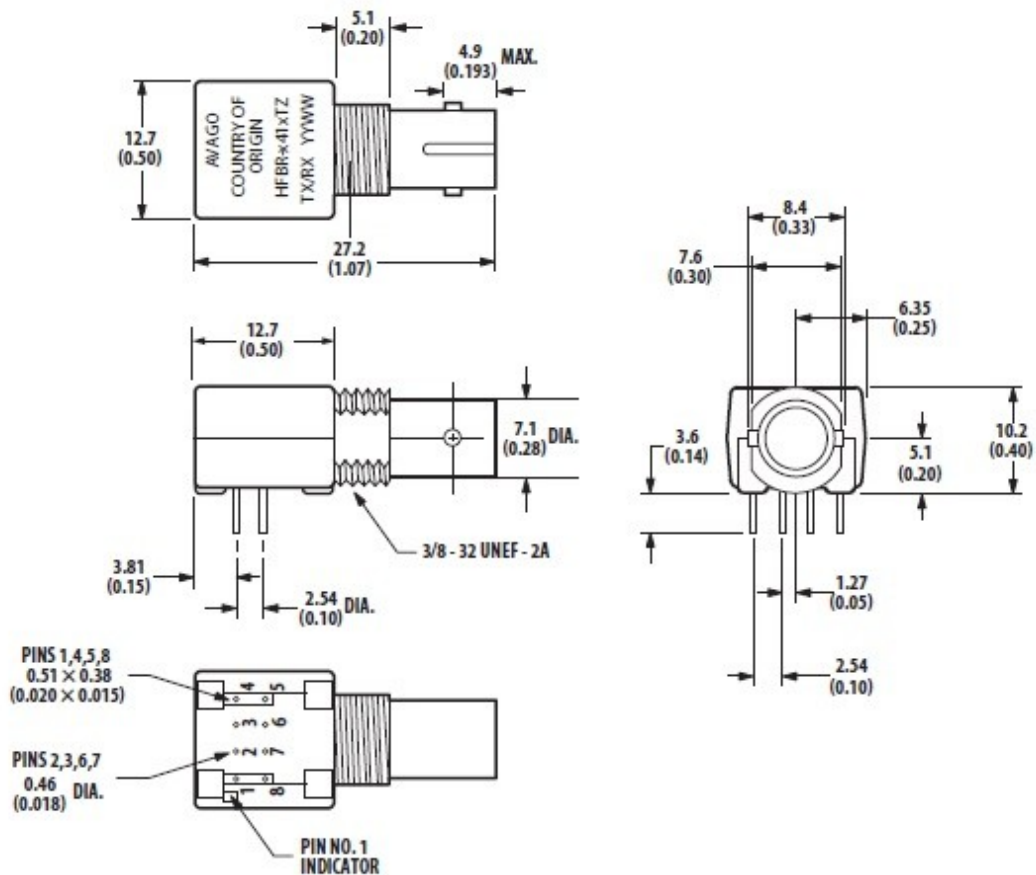
Dimensions in mm (inches)

6 ORDER CODES

Here below the order codes :

CODE	DESCRIPTION	PICTURE
ST0N 1625NC\SR	Device with support for din rail bar + 2 Fiber Optic Connectors	
ST0N 1625NK\SR	Device without support for din rail bar + 2 Fiber Optic Connectors	
ST0N 1625NC\DR	Device with support for din rail bar + 4 Fiber Optic Connectors	
ST0N 1625NK\DR	Device without support for din rail bar + 4 Fiber Optic Connectors	

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